



IAC-RK3568-Kit Android Test Manual

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QIYANG TECHNOLOGY Co., Ltd

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Version Record

| Version | Hardware Platform | Description | Date | Revisor |
|---------|---------------------|----------------------|---------|---------|
| 1.0 | IAC-RK3568-MB-V1_00 | Initial Version | 2022-08 | wangwx |
| 2.0 | IAC-RK3568-MB-V1_00 | Change some pictures | 2022-08 | wangwx |

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I .Preface

1.1 Company Profile

Zhejiang Qiyang Intelligent Technology Co., Ltd. was founded in Hangzhou in 2007, is a national high-tech enterprise focusing on the development, production and sales of ARM embedded products. 10 years of accumulation and precipitation, successfully built a product development to mass production service chain.

As the core of the company, Qiyang R&D team consists of more than 30 embedded engineers, dedicated to providing users with easy-to-use embedded hardware, software tools and customized product solutions. It has been widely used in industrial control, Internet of Things, new retail, medical, electric power, environmental monitoring, charging pile and other fields.

The production base in Zhuji provides a strong guarantee for Qiyang, covering an area of 5,000 square meters, with 2 SMT production lines, through and strictly follow the ISO9001 quality management system certification to guide production. Relying on the strong production strength, the annual production capacity can reach 1 million sets to ensure the delivery time of users and solve the worries.

Qiyang has a perfect sales and marketing network, professional sales and after-sales team to provide users with a full range of technical support and services. Business has spread to more than 120 countries and regions, successfully helping more than 2000 users to bring their products to market quickly and efficiently.

The combination and extension of R&D, production capacity and market has laid a solid foundation for Qiyang Intelligence to become a professional and global supplier of embedded software and hardware.

We offer:

- **Multi-platform software/hardware products**

NXP, Rockchip, MTK, Renesas, TI, Atmel, Cirrus Logic and other multi-platform ARM development boards/core boards/industrial control boards and peripheral hardware products, as well as supporting tools and software resources to support rapid secondary development of users.

- **Customized Services**

We fully utilize our accumulated technology on ARM platform and Linux, Android, Ubuntu and Debian operating systems to provide customized embedded product services (OEM/ODM).

Thank you for using Qiyang's products, we will do our best to provide you with technical assistance! Wish you good luck in your work!

II. Preparation

Read before testing: This manual mainly introduces the interfaces' functional testing on IAC-RK3568-Kit development board.

Please refer to **IAC-RK3568-Kit Hardware Manual**, **IAC-RK3568-Kit Debian & Android User Manual**, the development board has been loaded the firmware before leaving the factory, please test directly.

UART Debugging

Please test the UART by referring to the **IAC-RK3568-Kit Debian & Android User Manual**.

Power on the mainboard, connect to the Debug UART, then enter to the board's file system through Debug UART.

```
[ 24.144361] audit: audit_lost=1 audit_rate_limit=5 audit_backlog_limit=64
[ 24.144387] audit: rate limit exceeded
[ 24.150563] type=1400 audit(1677057105.730:89): avc: denied { bind } for comm="ip" scontext=u:r:qy_init:s0 tclass=netlink_route_socket permissive=1
[ 24.150780] type=1400 audit(1677057105.730:90): avc: denied { getattr } for comm="ip" scontext=u:r:qy_init:s0 tclass=netlink_route_socket permissive=1
[ 24.252870] IPv6: ADDRCONF(NETDEV_UP): can0: link is not ready
[ 24.252919] IPv6: ADDRCONF(NETDEV_CHANGE): can0: link becomes ready
[ 24.310275] IPv6: ADDRCONF(NETDEV_UP): can1: link is not ready
[ 24.355814] zram0: detected capacity change from 0 to 1026560000
[ 24.377143] IPv6: ADDRCONF(NETDEV_UP): can2: link is not ready
[ 24.428625] mkswap: Swap space size: 1002496k, UUID=83775dcc-8e36-4927-be91-60913bffdcc4
[ 24.430061] Adding 1002496k swap on /dev/block/zram0. Priority:-2 extents:1 across:1002496k
[ 25.264859] IPv6: ADDRCONF(NETDEV_CHANGE): can1: link becomes ready
[ 25.264988] IPv6: ADDRCONF(NETDEV_CHANGE): can2: link becomes ready
[ 25.870787] type=1400 audit(1677057107.456:94): avc: denied { write } for comm="RenderThyService" dev="tmpfs" ino=12876 scontext=u:r:priv_app:s0:c512,c768 tcontext=u:object_r:process_socket_file permissive=1 app=com.android.launcher3
[ 26.238366] audit: audit_lost=4 audit_rate_limit=5 audit_backlog_limit=64
[ 26.238401] audit: rate limit exceeded
[ 35.586335] vcc3v3_lcd0_n: disabling
[ 35.586416] vcc3v3_lcd1_n: disabling
[ 35.586450] pcie30_3v3: disabling
console:/ $
```

ADB Debugging

Please to do ADB debugging by refer to the **IAC-RK3568-Kit Debian & Android User Manual**.

The system enables adb debugging by default. If no adb device connection is detected, please check whether the jumper at the J5 pin header in the lower right corner of the development board is connected.

Note: All the following command are carried out under serial port debugging.

III. Mainboard Test

2.1 Display Test

It supports LVDS screen and HDMI screen.

7-Inch LVDS screen test:

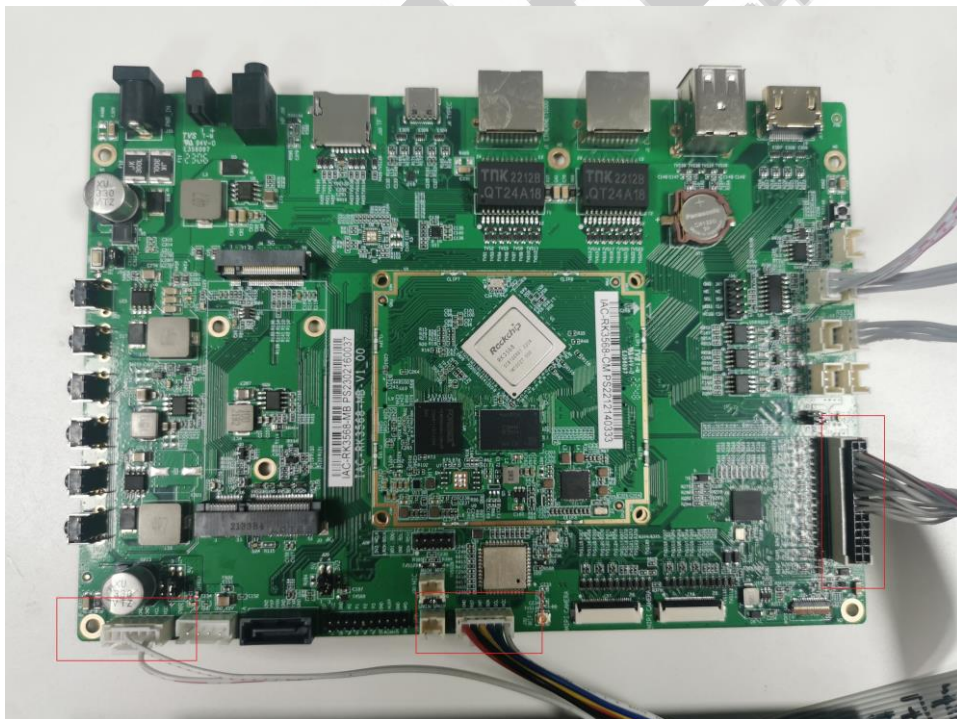
It supports the paired 7 inch LVDS screen (Capacitive Touch Panel), model no.: QY-HJ070NA-V1.2, resolution:1024x600. Please purchase it additionally, if required.

LVDS port-J19, (Please pay attention to J48 (Power Interface) jumper wire, 3.3V)

LVDS displayer backlight port: J25, (Please pay attention to J24 (Power Interface) jumper wire, 5V)

I2C capacitive touch panel -J23

Connection diagram between the mainboard with LVDS screen:



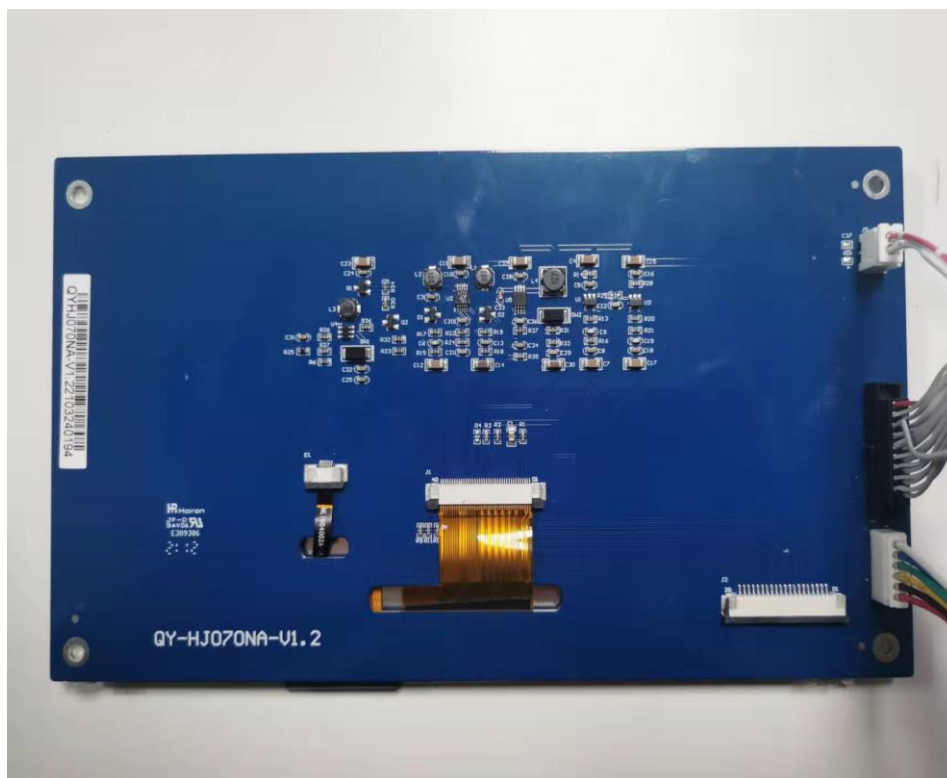
Any question, please send E-mail :supports@qiyangtech.com

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When the system starts normally, you can see the LCD screen shows the Android system interface.

If you do not purchase a 7-inch LVDS screen, you can use an HDMI monitor for testing.

2.2. WIFI Test

The onboard wifi chip AP6212 on the development board supports 2.4Ghz frequency band. Please make sure that the J32 wifi antenna is connected normally and whether the connected network is 2.4G.

Serial debugging operational interface: Input **ifconfig** to check whether wlan0 node is

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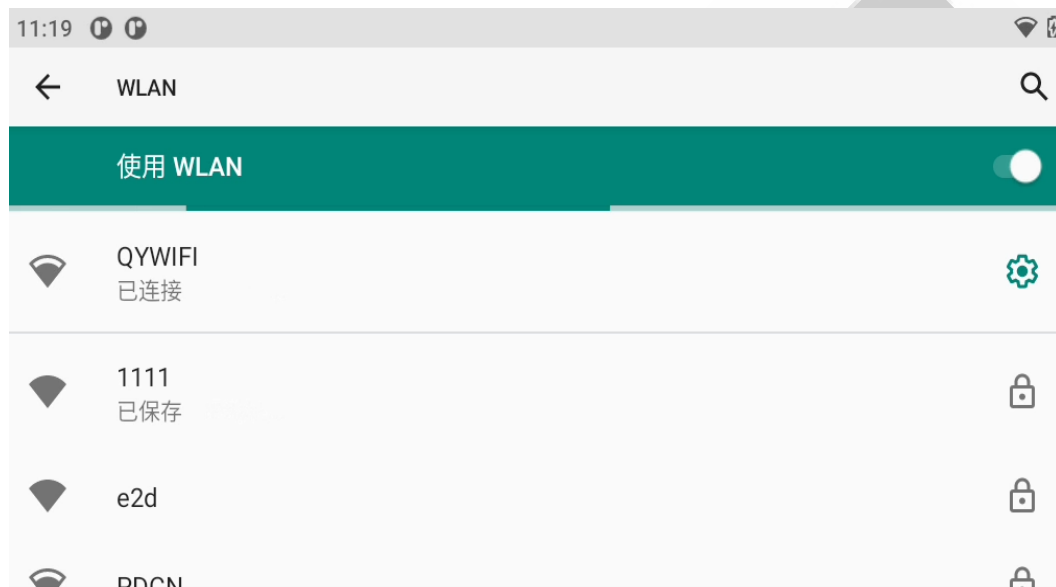
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generated

```
console:/ # ifconfig wlan0
wlan0   Link encap:Ethernet  HWaddr 08:e9:f6:9f:f2:d2  Driver bcm5dh_sdmmc
        BROADCAST MULTICAST  MTU:1500  Metric:1
        RX packets:0 errors:0 dropped:0 overruns:0 frame:0
        TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
        collisions:0 txqueuelen:1000
        RX bytes:0 TX bytes:0
```

GUI : Settings->Network and Internet->WLAN, connect to wifi for Internet testing

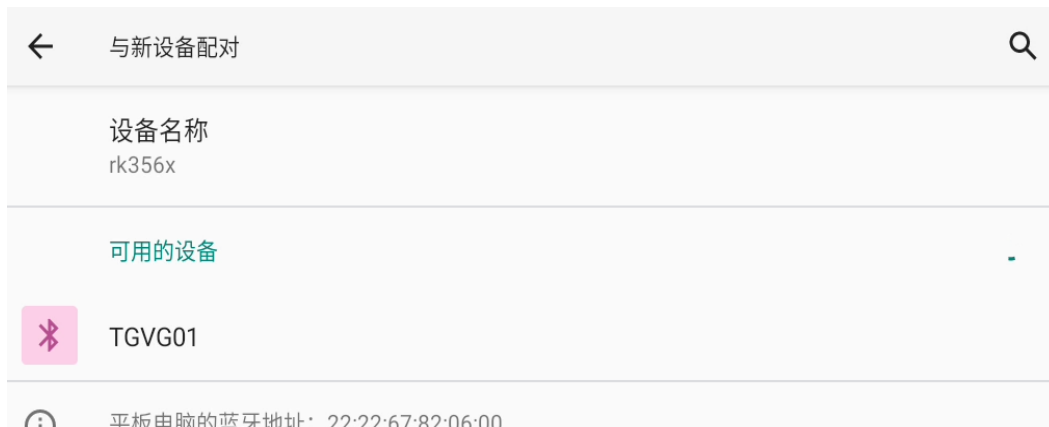


2.3. Bluetooth test

The development board has a Bluetooth chip AP6212 onboard, which supports Bluetooth 4.1 (BLE is not supported), please check the J32 antenna is connected.

GUI: Settings -> Connected Devices -> Pair New Devices -> Connect Bluetooth Devices

Start file transmitting and receiving test



2.4. LAN Test

The development board is equipped with two Gigabit Ethernet J2 and J1.

J2 corresponds to eth0,

J1 corresponds to eth1,

The PHY chip is on the backside of the carrier board. The current version is YT8531. If the LAN port does not work, please check the PHY chip on the backside, whether they are consistent. If not, you can contact our sales or FAE for help.

Serial debugging operational interface: Input **ifconfig** to check whether eth1 and eth0 nodes are generated

```
eth1    Link encap:Ethernet  HWaddr ee:39:67:49:23:70  Driver rk_gmac-dwmac
        inet addr:192.168.1.229  Bcast:192.168.1.255  Mask:255.255.255.0
        inet6 addr: fe80::f375:d411:42ab:2801/64 Scope: Link
        UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
        RX packets:25  errors:0  dropped:0  overruns:0  frame:0
        TX packets:18  errors:0  dropped:0  overruns:0  carrier:0
        collisions:0 txqueuelen:1000
        RX bytes:4440 TX bytes:2206
        Interrupt:46

eth0    Link encap:Ethernet  HWaddr f2:39:67:49:23:70  Driver rk_gmac-dwmac
        inet addr:192.168.1.245  Bcast:192.168.1.255  Mask:255.255.255.0
        inet6 addr: fe80::7a59:6ffa:95b6:7878/64 Scope: Link
        UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
        RX packets:156  errors:0  dropped:1  overruns:0  frame:0
        TX packets:24  errors:0  dropped:0  overruns:0  carrier:0
        collisions:0 txqueuelen:1000
        RX bytes:16238 TX bytes:2642
        Interrupt:39
```

TCP Test

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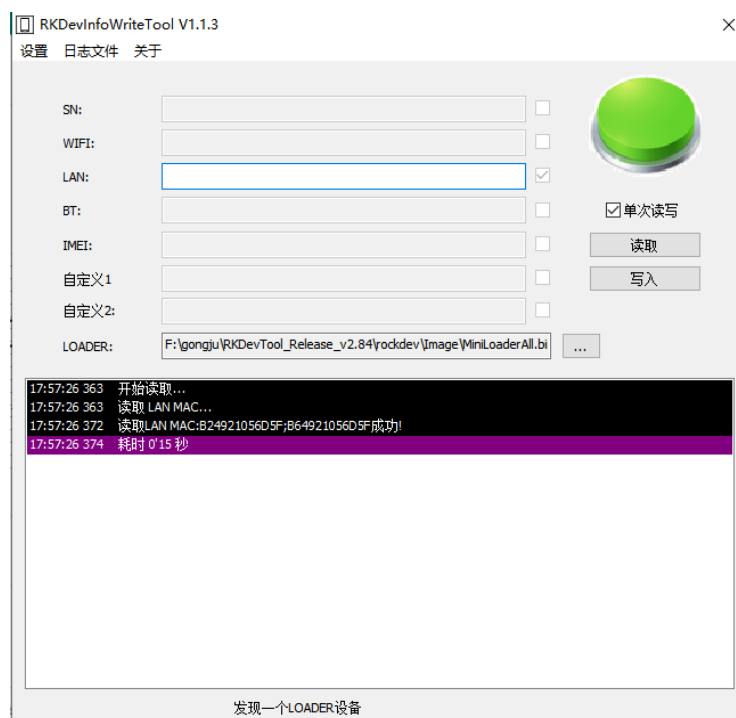
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```
console:/ #
console:/ # iperf -s -p 5001 -i 1 -M 1000M
WARNING: attempt to set TCP maximum segment size to 1048576000 failed.
Setting the MSS may not be implemented on this OS.
-----
Server listening on TCP port 5001
TCP window size: 1.00 MByte (default)
-----
[ 4] local 192.168.1.245 port 5001 connected with 192.168.1.9 port 44126
[ 968.189569] healthd: battery l=50 v=3 t=2.6 h=2 st=3 fc=100 chg=au
[ ID] Interval      Transfer      Bandwidth
[ 4] 0.0- 1.0 sec   112 MBytes   936 Mbits/sec
[ 4] 1.0- 2.0 sec   111 MBytes   935 Mbits/sec
[ 4] 2.0- 3.0 sec   112 MBytes   940 Mbits/sec
[ 4] 3.0- 4.0 sec   112 MBytes   938 Mbits/sec
[ 4] 4.0- 5.0 sec   112 MBytes   941 Mbits/sec
[ 4] 5.0- 6.0 sec   111 MBytes   935 Mbits/sec
[ 4] 6.0- 7.0 sec   110 MBytes   923 Mbits/sec
[ 4] 7.0- 8.0 sec   112 MBytes   936 Mbits/sec
[ 4] 8.0- 9.0 sec   112 MBytes   939 Mbits/sec
[ 4] 9.0-10.0 sec   110 MBytes   920 Mbits/sec
[ 4] 0.0-10.0 sec   1.09 GBytes   935 Mbits/sec
```

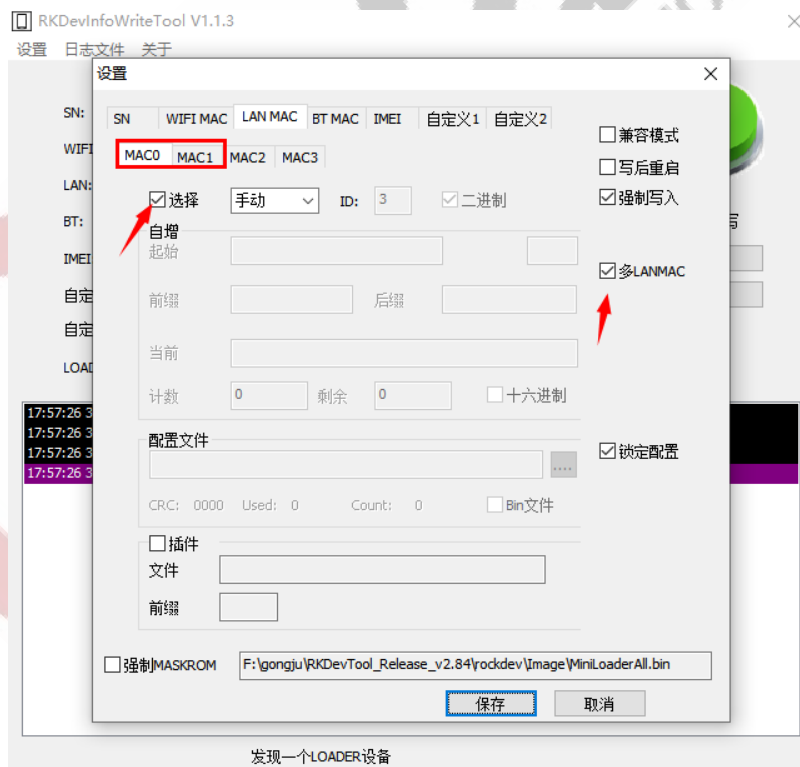
Modify MAC address:

It requires RKDevInfoWriteTool_1.1.3 in Windows if you want to change MAC address, open the software interface, it shows as below:

(Noted: The development board should enter to loader mode (Details, please refer to ***IAC-RK3568-Kit Debian & Android User Manual***)



Click Setting, then enter to the interface as below picture shown:



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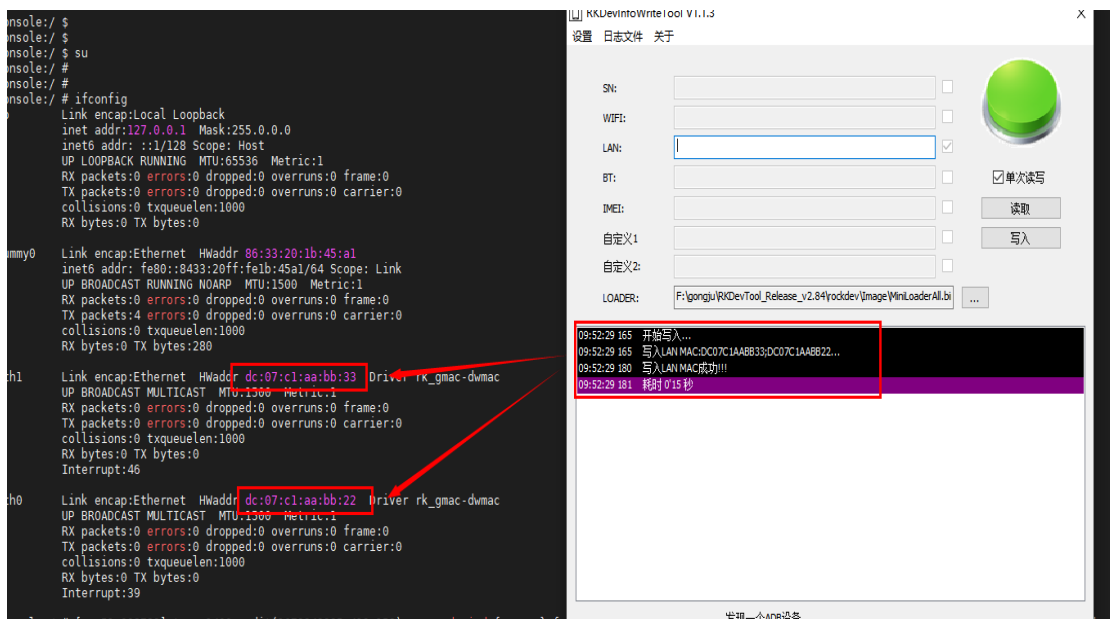
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Set, as the below picture shown:



2.5. RS232/RS485 Port Test

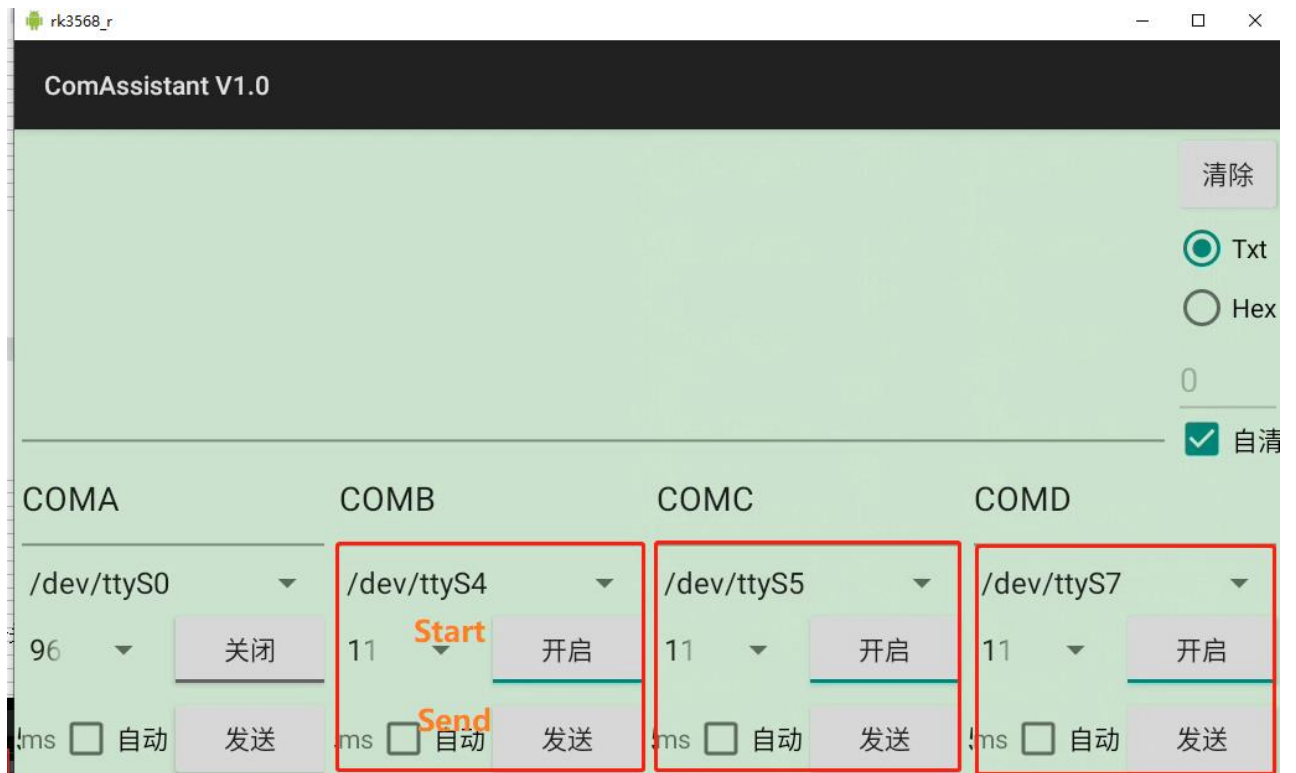
The development board is equipped with 4-ch serial port, of which J12 is the debug UART, J13 and J11 are RS232 port, and J10 is RS485 port.

All serial ports are from CPU, so be careful when testing to prevent core board from damage.

The software and hardware mapping relationship are shown in the table below

| Hardware Position | Device Node |
|-------------------|-------------|
| J10-RS485 | ttyS7 |
| J11-RS232 | ttyS4 |
| J13-RS232 | ttyS5 |

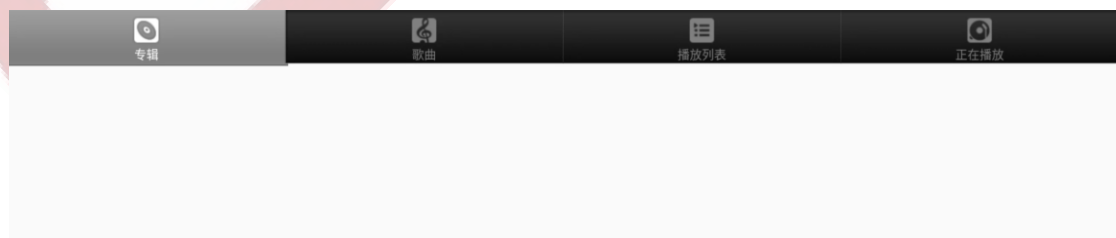
GUI Interface is as below picture shown:



2.6. Audio Test

The development board is equipped with two audio outputs and one audio input interface, of which J28 is HeadPhone interface, J31 is Speaker interface, and J30 is MIC interface, and the Speaker parameter is 8Ω/1.3W. Because the audio interface is directly out of the PMIC, please be careful when testing to prevent the core board from damage.

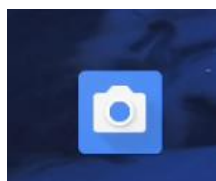
GUI Test: Music -> Play



2.7. Camera Test

The development board is equipped with two MIPI camera interfaces J26 and J27, which is adaptive to OV5648 by default. Here, we used the Android built-in camera application to test and open one camera J27.

GUI Interface:



2.8. 4G/5G Test

The development board is equipped with one M.2_ J4 port and one MINI-PCIE_ J3 port, among which the M.2 interface is adapt to the software protocol USB3.0, and the MINI-PCIE is adaptive to the software protocol USB2.0. By default, the board's adaptive 4G module is EC20, and the adaptive 5G module is RM500U-CN.

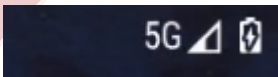
Serial port operational interface: Input **ifconfig** to check whether relevant nodes are generated, among which the 4G node is **wwan0**, and the 5G node is **usb0**

```
console:/ # ifconfig usb0
usb0      Link encap:Ethernet  HWaddr 6e:b9:fb:e3:32:ee  Driver cdc_ncm
          inet addr:10.17.49.41  Bcast:10.17.49.255  Mask:255.255.255.0
          inet6 addr: fe80::6cb9:fbff:fee3:32ee/64 Scope: Link
          UP BROADCAST RUNNING MULTICAST  MTU:1500  Metric:1
          RX packets:29  errors:0  dropped:0  overruns:0  frame:0
          TX packets:46  errors:0  dropped:0  overruns:0  carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:2653 TX bytes:3663
```

PING command test:

```
console:/ # ping www.baidu.com
PING www.a.shifen.com (112.80.248.75) 56(84) bytes of data.
64 bytes from 112.80.248.75: icmp_seq=1 ttl=54 time=58.2 ms
64 bytes from 112.80.248.75: icmp_seq=2 ttl=54 time=75.4 ms
64 bytes from 112.80.248.75: icmp_seq=3 ttl=54 time=41.4 ms
64 bytes from 112.80.248.75: icmp_seq=4 ttl=54 time=39.9 ms
64 bytes from 112.80.248.75: icmp_seq=5 ttl=54 time=38.4 ms
64 bytes from 112.80.248.75: icmp_seq=6 ttl=54 time=40.1 ms
64 bytes from 112.80.248.75: icmp_seq=7 ttl=54 time=35.9 ms
64 bytes from 112.80.248.75: icmp_seq=8 ttl=54 time=37.4 ms
64 bytes from 112.80.248.75: icmp_seq=9 ttl=54 time=33.2 ms
64 bytes from 112.80.248.75: icmp_seq=10 ttl=54 time=33.4 ms
64 bytes from 112.80.248.75: icmp_seq=11 ttl=54 time=29.3 ms
```

GUI:

A screenshot of a mobile device's status bar showing a 5G network connection icon, a signal strength indicator, and a battery icon.

2.9. CAN BUS Test

There are 3-ch CAN bus on development board, all of which come directly from the CPU. At present, the RK3568 CAN bus may cause frame errors when sending extended frames. Please to do multiple tests if you are using standard frames. And it is recommended to have external connection while using extended frames.

The mapping relationship between software and hardware is shown in the table

| Hardware Position | Device Node |
|-------------------|-------------|
| J14 | can0 |
| J15 | can1 |
| J16 | can2 |

Serial port operational interface: Input **ifconfig** to check whether there is a can node generated

```
console:/ # ifconfig
can1      Link encap:UNSPEC    Driver rockchip_canfd
          UP RUNNING NOARP  MTU:16  Metric:1
          RX packets:3 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:10
          RX bytes:24 TX bytes:0
          Interrupt:65

can2      Link encap:UNSPEC    Driver rockchip_canfd
          UP RUNNING NOARP  MTU:16  Metric:1
          RX packets:5 errors:0 dropped:0 overruns:0 frame:0
          TX packets:1 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:10
          RX bytes:40 TX bytes:8
          Interrupt:66

dummy0    Link encap:Ethernet  HWaddr 76:6e:53:f9:1a:ec
          inet6 addr: fe80::746e:53ff:fef9:1a:ec/64 Scope: Link
          UP BROADCAST RUNNING NOARP  MTU:1500  Metric:1
          RX packets:0 errors:0 dropped:0 overruns:0 frame:0
          TX packets:9 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:0 TX bytes:630

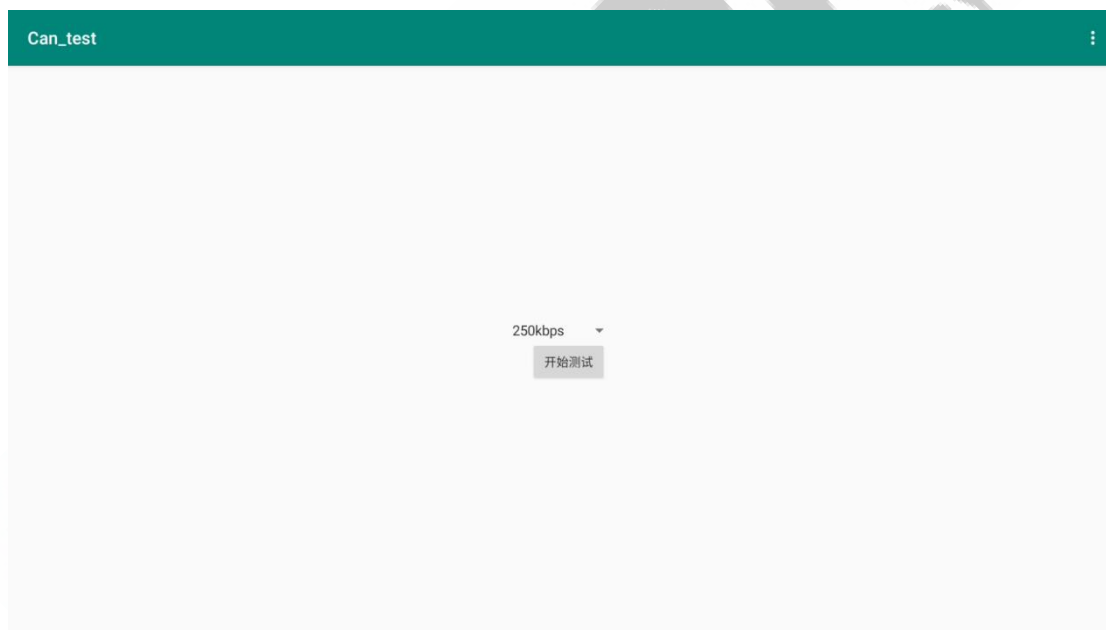
can0      Link encap:UNSPEC    Driver rockchip_canfd
          UP RUNNING NOARP  MTU:16  Metric:1
          RX packets:2 errors:0 dropped:0 overruns:0 frame:0
          TX packets:0 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:10
          RX bytes:16 TX bytes:0
          Interrupt:64
```

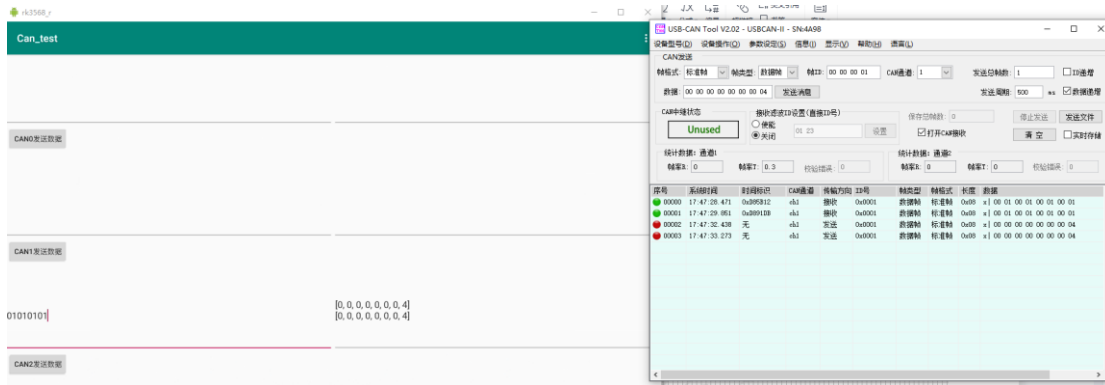
To connect CAN analyzer

Test command: **can_test can0 1/0** 1: Send 0: Receive

```
console:/ #  
console:/ # can_test can2 1  
CAN Start Testing ...  
send can datas: can_id = 0x123,data_len = 8  
data[0] = 0x0  
data[1] = 0x1  
data[2] = 0x2  
data[3] = 0x3  
data[4] = 0x4  
data[5] = 0x5  
data[6] = 0x6  
data[7] = 0x7  
Test Success.  
console:/ #
```

GUI Interface: Open **can_test APK**, select Bit Rate, then start the test. Here, 250k is selected.





IV.Summary

Till now, the basic functional tests are all done, if any errors, please check the test code.

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